

Use of the High Resolution Profiler (HRP) in the Brazil Basin Tracer Release Experiment

by

Ellyn T. Montgomery

March 1998

Technical Report

Funding was provided by the National Science foundation through Grant No. OCE-94-15589

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 τ *turna m.* **Terrence M. Joyce, Chair**

Department of Physical Oceanography

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Abstract

On two research cruises in 1996 and 1997 aboard the *R/V Seward Johnson,* scientists from the Woods Hole Oceanographic Institution participated in a study of the deep mixing processes in the Brazil Basin. Two instrument systems were used in this experiment: the tracer injection and sampling system, and the High Resolution Profiler (HRP). The HRP component of the work at sea, instrumentation, data return and some preliminary results are presented in this report.

The first cruise (96-01) departed from Rio de Janeiro, Brazil, on January 22, 1996 and returned to Recife, Brazil, on February 27 with most of the work occurring in the eastern part of the Brazil Basin. During the cruise, one patch of sulfur hexafiuoride (SF6) tracer was injected successfully in the area around 21°42' S, 18°28' W, in a series of 8 streaks injected over 7 days. The patch was successfully sampled twice, verifying the initial tracer concentrations. The HRP was used to make two zonal sections across the basin, sample the injection site, and explore the mixing dynamics above the jagged seafloor near the Mid-Atlantic Ridge; 75 full depth HRP profiles were completed.

The second cruise (97-01) departed from Recife on March 13, 1997, and returned on April 18. The goal of this cruise was to sample and map the patch of tracer injected in 1996. By mapping the tracer's distribution one year after deployment, an indirect estimate of the rate and extent of diffusive mixing can be made. When possible, CTD casts and HRP profiles were done simultaneously to allow direct comparison of the data from the two instrument systems. A total of 77 CTD casts and 90 HRP profiles were completed, and within the accuracy of measurement, all the tracer deployed was found.

Overview

The first part of the Brazil Basin Tracer Release Experiment (BBTRE) took place in early 1996. The objectives of this cruise were to use the High Resolution Profiler (HRP) to complete an intial survey of the dissipation and diffusivity rates observed in the Brazil Basin, and to inject two patches of sulfur hexafluoride (SF6) tracer that would be sampled a year later. The tracer and HRP systems provide independent estimates of the turbulent mixing rate. The deployment and subsequent sampling of a tracer as it is mixed over time is an integrated way of estimating mixing. The sensors on the HRP allow discrete estimates of mixing to be made. Obtaining consistent estimates from two different methods gives a more convincing result than obtaining just one kind of estimate.

The injection cruise was highly successful despite minor instrument problems. Tracer injections were planned at two sites, but injection sled malfunctions made deploying tracer at the first site impossible, despite several attempts. The sled systems were debugged and working well by the end of the first cross-basin HRP survey. Using the HRP, a site with active deep mixing (at 21°42'S, 18°28'W) was chosen for the tracer injection. Eight streaks of tracer were successfully injected at 4000 meters depth at the site. Several neutrally buoyant pop-up floats were deployed to track the tracer movement. They were programmed to surface and transmit their positions after a year.

While surveying the basin for a suitable injection site and during the tracer injections and sampling, 75 HRP profiles were completed. HRP dives 1-8 were at the base of the Continental Shelf, in the area near the Deep Western Boundary Current. Dives 9-25 and 65-75 comprised two cross-basin sections. Dives 26-44 and 62-64 were completed as repeated surveys of a ridge near the tracer injection site. Areas of rough bottom topography on the western flank of the Mid-Atlantic Ridge were sampled in dives 45-61. A map of the Brazil Basin showing the locations of HRP profiles made during the cruise is shown in Figure 1. An enlargement of the injection site shows tracer injection streaks and locations of the floats deployed to follow the tracer.

The second part of the experiment occurred 14 months later, in the of spring of 1997. The goal of that cruise was to find the tracer injected in 1996 and to map its distribution. Bottle samples taken during CTD casts were analyzed using gas chromotography to quantify SF6 levels and distribution. The HRP profiles provided additional discrete estimates of diffusive mixing.

All the work of the second cruise was concentrated around the tracer injection site. The pop-up floats had surfaced and reported their positions in January 1997, suggesting rates and directions of movement of the water to which the tracer had been applied. A cruise plan was made that would thoroughly sample the area over which the tracer was expected to be distributed, based on the floats' data.

The HRP stations made on the sampling cruise are shown in Figure 2. They were contemporaneous with CTD casts whenever possible. The first 30 stations were made working eastward up a canyon approaching then leaving the injection site. Then the CTD winch failed, and ten HRP stations were made up and over the crest of the Mid-Atlantic Ridge with no accompanying CTDs. By dive 41 the winch was fixed, and the rest of the HRP profiles all have accompanying CTD data,

Figure 1: Chart showing the Brazil Basin injection cruise HRP dive locations. Enlargement shows the locations of the SF6 tracer injection streaks and the positions of the floats deployed to track the tracer.

Brazil Basin Tracer Release Experiment II- HRP profiles

Figure 2: Chart showing the locations of HRP dives made during the sampling cruise

despite more winch problems. HRP dives 41-80 completed the southern part of the survey; then the final ten stations mapped the tracer distribution north of the injection site.

The emphasis of this report will be on the HRP work completed during both cruises: the tracer component will be documented elsewhere. A description of the HRP, cruise logs, data summaries and some preliminary results are presented in the sections following.

The scientists participating in this study are listed below; those who only made one cruise are noted.

Cruise Log — Injection Cruise — Year 1

The *R/V Seward Johnson* left Rio de Janeiro, Brazil at 1900h on January 22, 1996, in warm sunny weather. As we left the coast, that evening, we were treated to a spectacular show of thunder storms over land. A section across the continental shelf and slope was planned, but the Brazilian government did not grant the project clearance, so we transited directly to the site of the proposed first tracer injection (25.0°S, 38.58°W), arriving late on January 23.

Work commenced with the deployment and recovery of the weight that steadies the injection sled to demonstrate the capacity and reach of the ship's crane. When the sled weight was back on deck, two test deployments of the HRP were completed. The first was to 1000 meters to allow a review of operations and to find any component systems failures. The second was a deep dive to test the depthfinder system, profiling to within 77 meters of the bottom. Then, since the sled was not ready for deployment, another full depth HRP dive was done.

The injection sled was deployed for movement control and engineering systems tests on January 25 at 0000h. The sled was recovered six hours later to fix problems encountered during the tests. While the sled systems were being diagnosed and debugged, four more HRP dives (4- 7) were completed, beginning a short transect at the bottom of the continental slooe. The sled

was ready to go in the water again January 26 at 0200, so HRP operations were stopped and the sled was deployed. The next set of tests was successful, so the first tracer injection was started. Unfortunately, the orifices that disperse the tracer were not working correctly at the target pressure, so the injection was terminated early in order to get the sled back on deck to work on the problem. HRP dive 8 was completed while the sled was being overhauled. The sled went back in the water at 0300h January 26, and unfortunately, the pumps failed soon after the injection was started. The sled was recovered and HRP dive 9 was done at the injection site. Due to time constraints, the scientists decided to abandon this site and concentrate on getting the problems with the sled fixed during the transit to the second site, near the Mid-Atlantic Ridge.

At 1550h January 27, the *R/V Seward Johnson* got underway on the first section across the Brazil Basin. The transect progressed smoothly, with 16 more HRP dives (all to within 50 meters of the bottom), interspersed with 10 RAFOS float deployments. Consistently sunny, fair weather let this work proceed quickly and smoothly. At the end of the transect a total of 26 HRP profiles had been completed.

On February 3, the ship had reached 21°33'S, 18°5'W, a location in the eastern part of the basin, over the deep flanks of the Mid-Atlantic Ridge, the first where consistent deep mixing was observed. This site was chosen for the injection over the one originally proposed because the HRP showed little or no deep mixing there.

The first tracer injection run was started at 1800h February 3. Clogged orifices caused no tracer to be pumped, so the sled was recovered shortly after it reached its target depth of 4000 meters. A time series of HRP profiles was started next, and three dives (27-29) were completed before the injection sled was ready to go back in the water. After one false start, the sled was deployed and successfully injected SF6 to make the first streak on February 5. For the next week, a total of eight streaks of tracer was laid, with a RAFOS float deployed to sample and track each of the streaks. Two pop-up floats, programmed to surface in January 1997 and transmit their positions, were also deployed: one on February 8, just after streak 4; the other on February 11, during streak 7. The floats' positions in 1997 will determine where the tracer sampling is started. HRP profiles were done between tracer injection runs as time allowed: dives 31-44 were completed during the injections. These profiles continued the time series already mentioned, and started a survey across a small east-west trending ridge. The last tracer injection was completed at 1341h on February 12.

The next objective was to sample the tracer, to be sure it was injected where it was expected. Because the SF6 levels in the ocean are very low, any traces of it on the ship had to be removed before sampling was attempted. First, the injection sled was dismantled and its components were sealed in airtight wrappings and stored away. Then the ship was allowed to air for two days, permitting the SF6 to de-gas and decrease the potential for contamination. Finally, the sampling equipment was unpacked and the other sled assembled. During this process, between February 12 and 16, HRP profiles 45-61 were completed along a northeasterly track from the deployment site. Peaks and valleys along the flank of the Mid-Atlantic Ridge were extensively sampled by these profiles.

Having had a chance to de-gas, the ship returned to the tracer deployment site on February 16 at 2000h, when the first sampling run with blanks was done. Three sampling runs were completed over the next 5 days. Since the sampler takes 4 hours each for deployment and recovery, and collects water over an eight hour period, the ship is fully committed by towing the collecting sled for at least 16 hours/tow. One HRP dive was done between each sampling tow to occupy the time required to collect the water samples and turn the sled around. The tracer patch was sampled successfully, with the highest concentrations of SF6 observed at 4000 meters, where it had been injected.

On February 21, a final RAFOS float was deployed at the injection site, and the transit to Recife, Brazil was started. On the steam to port, ten HRP profiles (66-75) were completed, sampling across the Brazil Basin north of the track previously sampled. The *R/V Seward Johnson* arrived in Recife at 1130h on February 27, after 35 days at sea. A detailed listing of the HRP profiles made during the injection cruise is presented in Appendix 1.

Cruise Log — Sampling Cruise - Year ²

R/V Seward Johnson departed Recife, Brazil on March 13, 1997 at noon, in pouring rain steaming southeastward to the injection area. In order to maximize the time spent sampling, no repeat HRP section between Recife and the injection site was planned, so a 5 day transit was expected. Each day during the steam, a stop was made to test either the CTD or HRP. Various instrument, winch and communications related problems were detected and subsequently fixed. We arrived at the site of the first sampling station, west of the injection site on March 18, at 2000 GMT.

This trip had no weather heavy enough to suspend operations. Slightly stronger winds and heavier seas were experienced than on the previous cruise, but it was still basically fine weather throughout. Two swim calls provided pleasant diversions from the shipboard routine.

The work in the injection area was commenced with HRP profile 3 on March 18. The CTD system was not ready to go, so we steamed east and did another HRP profile. After that HRP profile was completed, the CTD was deployed. Several casts were required to have the bottles fire successfully. No tracer was found in these water samples. At the next station a CTD profile was made, but no bottles fired, so the HRP was deployed while more CTD repairs were made. When the HRP was recovered, another CTD profile was made, the bottles closed successfully, and SF6 was found in some of the samples! It was nice to find tracer so soon, verifying the analytic technique was working as expected.

We wanted to maximize the area sampled during the cruise, so our goal was to do a CTD and a HRP profile at each station and then get underway to the next station, as quickly as possible. The main constraint was having the CTD secured on deck early enough to allow the ship to position itself for recovering the HRP. For much of the cruise, this was the sequence of events: the CTD was deployed, finished the downcast, started the upcast, the bottles were fired and then the HRP was deployed. During the HRP's descent, the CTD was recovered, the water samples collected, and then the ship was positioned to recover the HRP. The timing of operation required coordination between the groups and worked well after some initial changes.

The first survey line was planned to sample along the east-west trending valley that lies beneath the injection site. HRP profiles 3-27 (CTD's 3-27) were made on this line above the valley. HRP profile 12 was the closest to the injection site. Tracer was found much farther east than expected, and only decreased significantly after CTD 25.

The site where HRP and CTD 28 were deployed was offset from where it was planned to be, and, as a consequence, the water was 1500 meters shallower than expected. Unfortunately, as a result of the incorrect assumed bottom depth (the PDR bottom trace was hard to read), both the HRP and CTD hit bottom. Fortunately, neither instrument was badly damaged; the HRP was repaired before we arrived at the next station.

An excursion onto the Mid-Atlantic Ridge followed the initial sampling line in the valley. The first year's data suggested that deep mixing was enhanced in the eastern part of the basin over the rougher topography associated with the flanks of the Mid-Atlantic Ridge. The easternmost HRP profile last year was at 16°W, and we wanted to obtain profiles that would complete the section up to the Mid-Atlantic Ridge crest at about 11°30'W. HRP profiles 29-40 taken between March 26 and 28 comprise a loop onto the ridge and back to a position slightly south of the first line, from which the westbound sampling line was started. CTD profiles were not made in association with HRP profiles 29-40. The HRP acquired profiles over all sorts of bathymetric features during this side trip, and all showed high levels of turbulent mixing well into the water column, not just near the bottom.

Because no CTD's were done with the HRP profiles on the Mid-Atlantic Ridge, the numbers assigned to the HRP and CTD profiles were no longer the same. From HRP dive 41 until HRP dive 59, the number of the CTD cast associated with the HRP dive is (HRP dive $\#$ minus 11).

On March 28 at 1622h, CTD cast 30 was started, followed by HRP dive 41 to begin the next sampling leg. This leg went westward along an elevated ridge-like feature. The last station on this line was HRP dive 55, taken in the early morning of April 1.

Another eastward line, again in a valley, south of the first and second lines was then started. HRP dives (with concurrent CTD sampling) 56-65 comprise this line, which was finished on April 5. The traction head on the winch failed during CTD 48, causing near loss of the CTD package, but heroic efforts returned the CTD to the surface. Unfortunately HRP 59 had already been deployed when the failure occured. Since the CTD was still stuck at about 4500 meters when the HRP was due to surface, the ship's zodiac was used to return the HRP to the ship for recovery. It was determined that the winch was unrepairable, and that the CTD cable would have to be spooled onto the drum of the older, slower Markey winch. Operations were fully underway again 2 days later, after repairs and tests had been completed.

HRP dives 66-72 were taken on another more southerly westbound line, and HRP dives 73- 80 were taken on the southernmost eastbound line. On these lines, ridges and valleys were sampled alternately. These stations took 5 days to finish with dive 80 completed on April 11. Tracer levels found in the water samples decreased to barely detectable levels as the ship progressed southward. Since shiptime was running out, the decision to transit to a point north and east of the first line was made. This plan optimized the time left by finishing the last sampling in the direction of port.

The final sampling line was started late April 11, and was comprised of HRP dives 81-90. The steam back to Recife was started immediately following the last HRP profile, which was done with CTD 78 on April 14. We arrived at the dock as scheduled on April 18, after an extremely productive research cruise. A detailed listing of the HRP dives made during the sampling cruise is presented in Appendix 2.

HRP Instrument Description

The High Resolution Profiler (HRP) is an oceanographic instrument designed at WHOI to collect fine- and microstructure data during vertical profiles. A schematic of the HRP's structure and component systems is shown in Figure 3.

To minimize ship-induced noise in the measurements, the HRP dives without attachment to the ship. It is deployed, falls freely while collecting data (which it stores in 16 Mb of on-board RAM), drops its weights at a user-specified pressure, stops data acquisition, puts the computers in a wait state to conserve power, and rises to the ocean surface where it can be recovered. Once back on deck, the data are downloaded from instrument memory to a shipboard computer where analysis and archiving occur.

The HRP has two profiling modes: fine and micro, with the transition between them triggered by the CTD's pressure reaching user-defined threshold values. Fine sensors (including the CTD) are sampled at 10 Hz, and microstructure sensors are sampled at 200 Hz, with fine sampling continuing throughout the period of micro sampling.

Up to 16 sensors may be added to the HRP to complement the basic CTD measurements. The profiler is designed for versatility, so its configuration is determined by whichever suite of sensors is connected to the available channels. The configuration used for this experiment follows:

Figure 3: Cutaway view of the HRP component systems

At a nominal descent rate of 0.6 meter/second, a 4000-meter dive takes 2 hours for descent, and ¹ hour for ascent. During the dive, two megabytes of fine data and twelve megabytes of micro data will be acquired and stored, given the sensor configuration shown above. The transfer of data from the HRP is accomplished using a serial (RS232) connection operated at a nominal speed of 57.6 Kbaud. The actual speed obtained is about 45 Kbaud, which means it takes about an hour to transfer the data from the HRP to computers on the ship. Adding some time to maneuver during recovery, it takes 4 1/2 to 5 hours to complete a deep HRP profile.

To quantify the deep mixing accurately, close approaches to the bottom in areas of rough and rapidly changing bottom topography were required. Our experience with the Datasonics 900 altimeter that was interfaced to the HRP for the Abrupt Topography Experiment (TOPO) program (and used during the Circulation in the Romanche Fracture Zone Experiment (CIRFZ)) indicated the system would provide reliable ranges over flat seafloor, but perform less reliably over slopes. Prior to this cruise, software and hardware changes were incorporated and tested to allow the acoustic altimeter to function more robustly.

Often, the first good return occurred at about 150 meters from the bottom and ranges were received with little drop-out, however, other profiles lost as much as 50% of the expected altimeter data. Figure 4a shows all the altimeter data from the last 4 minutes of injection cruise's dive 31. Note the high rate of data return and that the furthest range detected was at 158.6 meters. An enlargement of the last 50 ranges is shown in Figure 4b, and shows occasional missing data, but generally good rates of return. Appendix 3 provides a list of how close to the bottom the HRP got on each profile during the injection cruise and which criterion caused dive termination.

During the second year cruise, there were only six incorrect dive terminations based on range. These were cases where a character in the range data stream was dropped, causing an early termination. Ninety-three percent of the profiles terminated correctly by either the range or pressure thresholds being met.

The HRP had several close calls with fate during this experiment. Early in the first cruise, the ship struck the profiler on recovery, gouging the protective skin. The damaged section was replaced immediately and the HRP was re-deployed. On the next dive, the profiler was again hit on recovery. This time it was brought on deck with only one of the four nuts that attach the floatation at the top of the instrument to the electronics case on the bottom still in place. Needless to say, all the nuts were replaced and carefully tightened before it went in the water again.

The HRP work continued uneventfully until dive 58, when part of one of the batteries that power the computer leaked and drained without the lowered capacity showing up in the pre-dive checks. The diminished power level allowed correct functioning on deck, but at cold temperatures

Figure 4: (a) altimeter data from the last 4 minutes of profile 31; (b) enlargement showing the last 50 altimeter returns.

encountered at depths greater than 4000 meters, the battery failed to run the release solenoids, causing the HRP to continue descending until it hit the bottom. Eventually the corrosible links broke and the HRP began to surface. No major structural damage occurred, but the microstructure probes all had to be replaced. The HRP hit the bottom twice more during the cruise, neither time causing significant damage: the first time it mysteriously failed to start logging, so consequently didn't have a way of knowing when to stop, and so went into the bottom; the second, a modification to the altimeter software had been downloaded but did not work as tested, causing a crash.

These incidents caused concern, but also showed the excellence of the original HRP design (kudos to the engineers involved!). Each time a problem caused a crash, one of the fail-safe release methods allowed the HRP to return to the surface, despite being stuck on the bottom for short durations. The shape, orientation and structure of the body and sensors have proved robust for the 5 cm/sec impacts encountered. So overall, the HRP has shown itself to be able to withstand the rigors of work in the deep sea.

For additional information on the development of the HRP, see the paper by Schmitt *et ed.,* (1988; 1995) for operational details of working at sea with the HRP see the technical report by Montgomery (1991); and development of the altimeter interface is documented by Montgomery and Schmitt (1997).

Data Processing

The first step in the data processing is transferring the raw data acquired during a dive to a shipboard computer via a fast serial transfer. The rest of the processing is completed on UNIX workstations using programs developed especially for use with the HRP. As soon as the data are transferred to the PC, the altimeter data are converted to ascii and checked to determine the range from the bottom at weight release. Often the pressure criterion terminates a dive before the altimeter criterion is reached. The altimeter returns from these profiles are used to evaluate the altimeter's successful functioning in areas of rough topography.

The fine and micro data are stored as counts in binary format. The next step of the processing is converting the raw numbers to scientific units, applying some nominal calibrations, and making quality control (QC) plots. The quality control plots can indicate problems with any of the sensors that should be fixed before the next deployment. Examples of the fine and microstructure QC plots using profile 31 from year ¹ are shown in Figures 5a-d.

As the QC plots are generated, a program is run that computes finescale velocity, plots potential temperature-salinity profiles, and bins the data in a uniformly incremented pressure series (typically 0.5 db). The velocity computation (Schmitt *et al,* 1988) uses the acceleration and magnetometer data to correct the raw acoustic current meter data for instrument motion. Laboratoryderived calibration data are used to convert raw pressure and temperature data to scientific units. A laboratory-derived relationship is also utilized for the initial estimate of the conductivity cell calibration. Adjustments of this scale are subsequently derived to obtain consistent deep water potential temperature-salinity relationships. The output is stored in binary format while a plot of

Figure 5: d. Microstructure quality control plot of differential temperature and conductivity, and shear for dive 31.

temperature, salinity, east and north velocities versus pressure is created. An example of this type of plot, again using profile 31 from year 1, is shown in Figure 6.

Microstructure data processing is started as soon as the data are transferred from the HRP but takes longer to complete, due to more densely sampled data and more computations performed. The scheme used follows procedures developed by Neil Oakey (Bedford Institute of Oceanography). A report by Polzin and Montgomery (1996) describes the microstructure data processing, so only a brief summary is included here.

The processing utilizes laboratory-derived calibration coefficients of the shear probes (microscale velocity sensors), while in-situ calibration data for the microscale temperature and conductivity sensors are obtained by reference to the finescale temperature and conductivity from the HRP. The microstructure data are binned in the time blocks aligned with the uniformly incrementing pressure series of the reduced finescale data. Gradient variances are estimated in the frequency domain after fast Fourier transforming by integrating spectra out to a local minimum in energy density. Spectral corrections are then applied for the finite responses of the sensors. After automated edit and consistency checking, scaling to scientific units yields estimates of the kinetic energy dissipation rate $(\epsilon, \text{ epsilon})$ and two measures of the dissipation rate of thermal variance (from the microscale temperature and conductivity sensors: chi-T and chi-C respectively). Profile plots (in "stick-diagram" form) of the dissipation rates are then produced, examples of which (again using profile 31, year 1) are shown in Figure 7.

The following is a short description of the enhancements made to the basic processing system during BBTRE. Three major software development feats were acomplished during this experiment. First, all the programs used for HRP processing were demonstrated to run (much faster) on the new SGI computers. Second, the functioning of these programs on the old DEC VAX computer and newer SGI ones was analyzed and the results compared. This allowed us to verify that the same program executed using the same data on each of the two machines produced the same results (within 0.05%). So now we can take only the SGIs to sea and be confident of the correctness of the results. Finally, and most fun, a Graphical User Interface (GUI) was developed for the suite of HRP processing programs by Tom Bolmer. Now, it is much easier to complete the data processing and generate the normal output.

Converting the HRP processing software to run on UNIX was fairly easy, but deciding where to prune antiquated files, formats and processes was more difficult. The "ctdvax" format and intermediate files of this type were eliminated during the port, and the format of the ".vel" file was changed, but routines were maintained or written to allow backward compatibility. The new programs on the SGIs have switches that allow the choice of input format.

The programs were also tested rigorously to verify that they work correctly. The numbers output by the programs and subroutines on the VAX were compared to those output by the SGIs to assure that no undetected errors were responsible for incorrect answers. The programs that work on the finescale data check out exactly, and the programs the accomplish the microstructure processing obtain very similar answers. The means of the final diffusivity estimates derived from the microstructure data differed by only 5e-12. We are confident that the programs now work robustly on the SGIs and generate answers that are statistically the same as those from the VAX.

Figure 6: Sample velocity plot from dive 31.

Figure 7: Stick plots epsilon, chi T and chi C.

Shell scripts to automate some of the processing steps replaced the equivalent VAX command files. These allow the operator to run several programs in sequence without doing the keyboard input by hand. The extension of writing the shell scripts to streamline the processing, was incorporating them into a Graphical User Interface (GUI) based system. The Tcl/Tk programming language was used to make the windows and call the processing scripts when the appropriate buttons are pressed. All the input needed for the programs can be entered in the GUI environment, and all the functions currently used in the at-sea HRP processing can be accessed. The UNIX processing system, the scripts used to automate running the programs and the GUI interface are documented in a report by Montgomery and Bolmer (in preparation).

Results

Both the Tracer and HRP groups felt this was a very successful experimental program. We worked well together utilizing the available shiptime to the fullest. During the first cruise approximately 114 kg of tracer was applied at a depth of 4010 meters in order to have initial concentrations of 0.04 M detected during the post-injection sampling runs. In 75 dives, the HRP was able to complete two cross-basin surveys, identify a site with active mixing at which to deploy the tracer, and sample ridge and valley areas of the flanks of the Mid-Atlantic Ridge.

During the second cruise, the tracer distribution was mapped and found to be spread over an area of $250,000 \text{ km}^2$. To within the detection limits of the sampling method, all the tracer deployed was accounted for in the second year's sampling. The 90 HRP dives completed provide instantaneous estimates of diffusivity and dissipation to compare with the estimates based on the tracer distributions. The estimates from the two methods agree quite well.

The cross-basin sections, acquired by the HRP during the injection cruise and extended during the sampling cruise, have made us rethink how deep mixing works. Fairly constant levels of mixing were expected across the basin, with enhanced mixing occurring near the bottom. In actuality, the two HRP transects showed the part of the Brazil Basin west of 28°W to have very low levels of mixing $(K\rho < 1e-5)$, and the eastern part to have much higher levels. As shown in Figure 8, there appears to be correlation between topographic roughness in the eastern basin and elevated levels of turbulent diffusivity. The highest levels of $K\rho$ are found near the bottom, but mixing is enhanced well into the mid-water. The papers by Polzin *et al.* (1997) and Toole *et al.* (1997) document the scientific results in greater detail than is presented here.

Figure 8: Contours of K_ρ from the two cross-basin HRP sections.

Appendix 1

HRP Deployment Positions for the Brazil Basin Tracer Release Experiment Injection Cruise: Year 1

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(Continued) HRP Deployment Positions for the Brazil Basin Tracer Release Experiment

Injection Cruise: Year 1

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 \sim \bar{z} (Continued) HRP Deployment Positions for the Brazil Basin Tracer Release Experiment ¹

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Injection Cruise: Year 1

Appendix 2

HRP Deployment Positions for the Brazil Basin Tracer Release Experiment

Sampling Cruise: Year 2

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(Continued) HRP Deployment Positions for the Brazil Basin Tracer Release Experiment

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Sampling Cruise: Year 2

(Continued) HRP Deployment Positons for the Brazil Basin Tracer Release Experiment

Sampling Cruise: Year 2

Appendix 3

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Range From Bottom at Dive End During BBTRE 1

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Range From Bottom at Dive End During BBTRE 1 (Continued)

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Range From Bottom at Dive End During BBTRE ¹ (Continued)

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